



# High Gradient High energy gain Inverse Free Electron Laser

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RUBICON collaboration*

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# Outline

- Radiabeam-UCLA-BNL IFEL COllaboration (RUBICON) experiment
- Most recent undulator design modifications
- Undulator construction status report
- Outlook and project schedule

# A new era for Inverse Free Electron Laser Acceleration scheme

- 2004 IFEL experiments: UCLA Neptune, BNL STELLA 2
- IFEL : a mature advanced accelerator scheme
  - Control of longitudinal phase space (prebunching)
  - 1D acceleration scheme
  - Efficient energy transfer
- Towards a mid-high energy range compact injector.
  - Helical IFEL undulator interaction.
- Applications as ICS or FEL based light source driver.



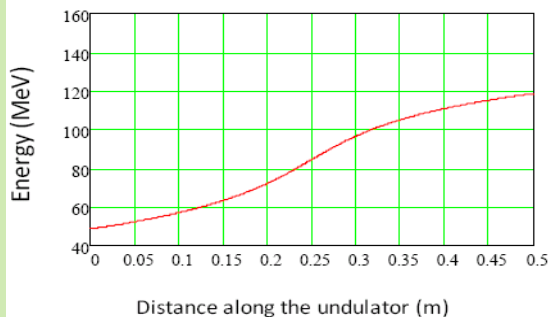
# Inverse Free Electron Laser Roadmap

- Renovated interest in IFEL acceleration scheme
- Applications as compact scheme to obtain 1-2 GeV electron beam for gamma ray (ICS) or soft x-ray (FEL) generation.

## Radiabeam UCLA BNL IFEL Collaboration

Strongly tapered optimized helical permanent magnet undulator

ATF @ BNL  
 0.5 TW CO<sub>2</sub> laser  
 50 MeV → 180 MeV in 60 cm  
 75 MeV energy gain  
 120 MV/m gradient

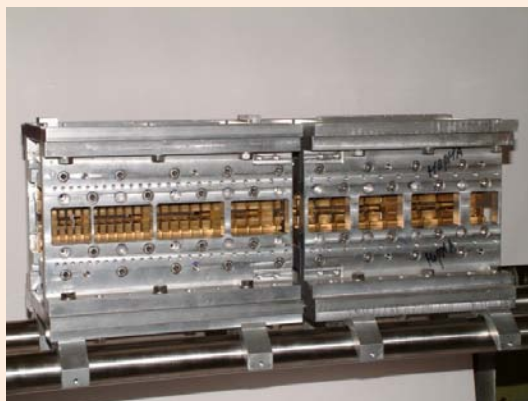


## LLNL-UCLA IFEL experiment

Reuse UCLA- Kurchatov undulator

Use 5 TW 10 Hz Ti:Sa  
 50 MeV → 150 MeV in 50 cm

High rep rate allows beam quality measurement



## GeV IFEL experiment

If current experiments successful

Looking for access to facility with 50 MeV beam+20 TW laser (BNL, LLNL, LNF-Italy)

Praesodymium based cryogenic undulator

Initial energy	50 MeV
Final energy	1200 MeV
Avg gradient	1.1 GV/m
Final energy spread	1 %
Laser wavelength	800 nm
Laser power	20 TW
Laser spot size ( $w_0$ )	0.2 mm

# Radiabeam Ucla Bnl IFEL Collaboration

## RUBICON

The experiment main goal is to achieve energy gain and gradient significantly larger than what possible with conventional RF accelerators to propose IFEL as a viable technology for mid-high energy range accelerators.

This can be achieved using the existing ATF e-beam and high power CO2 laser system

*TOGETHER WITH*

Helical geometry.

Permanent magnet double tapered undulator.

Parameter	Fixed Value
Initial $e$ -beam energy	50 MeV
Laser wavelength	10 $\mu\text{m}$
Laser peak power	0.5 TW
Nominal length of wiggler, $L_w$	60 cm
Rayleigh range	9 cm
Laser focal spot size ( $w$ )	550 $\mu\text{m}$
Location of laser waist inside wiggler	30 cm
Undulator length	60 cm

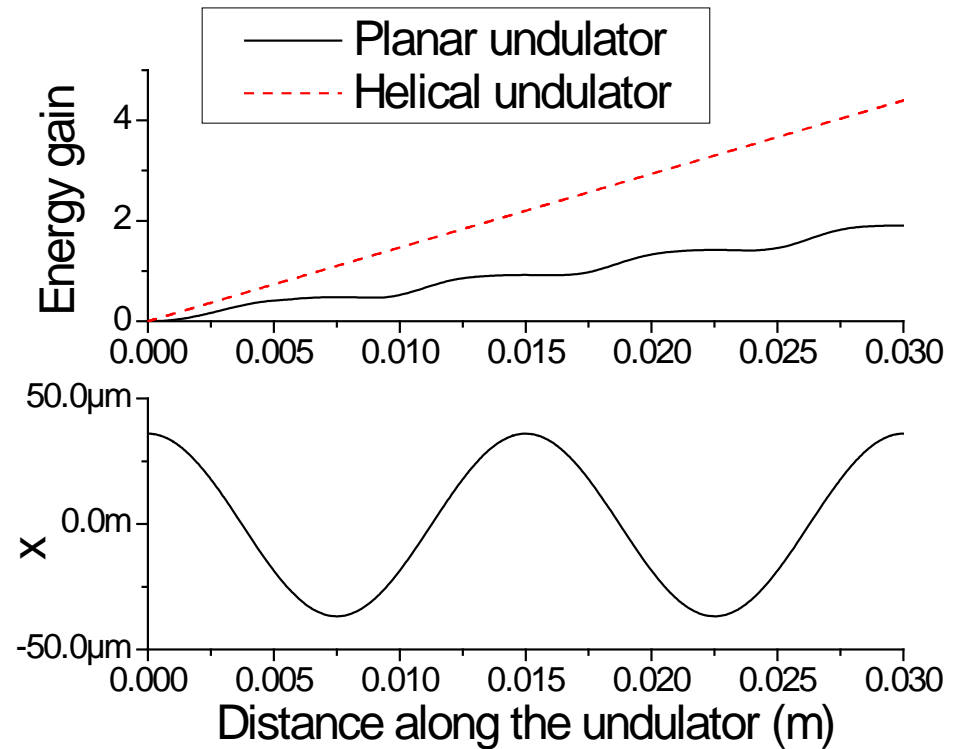
**Table 1. Parameters for BNL high gradient high energy gain IFEL experiment**

# Helical interaction

Works at least two times better.

Interaction with circularly polarized laser is always ON

Factor  $\sim 2.3$  extra gradient



Planar

$$\frac{\partial \gamma}{\partial z} = kK_1 \frac{JJ(K)}{2} \cdot \frac{K}{\gamma} \sin(\psi)$$

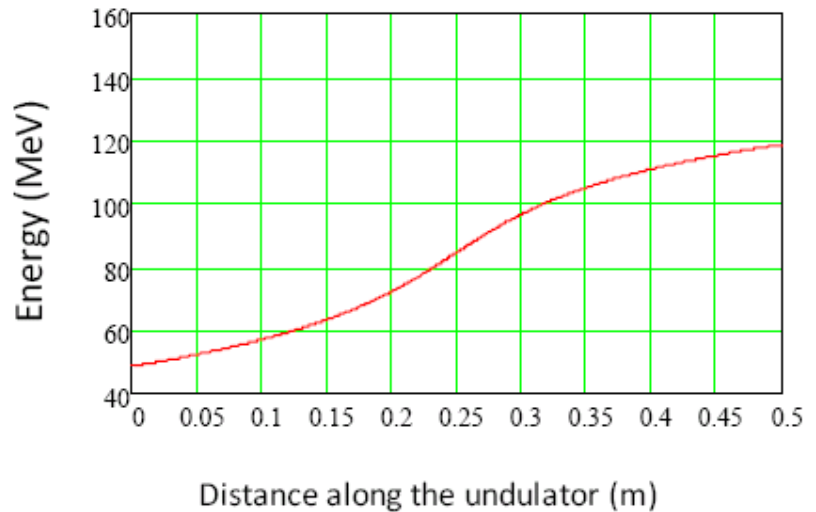
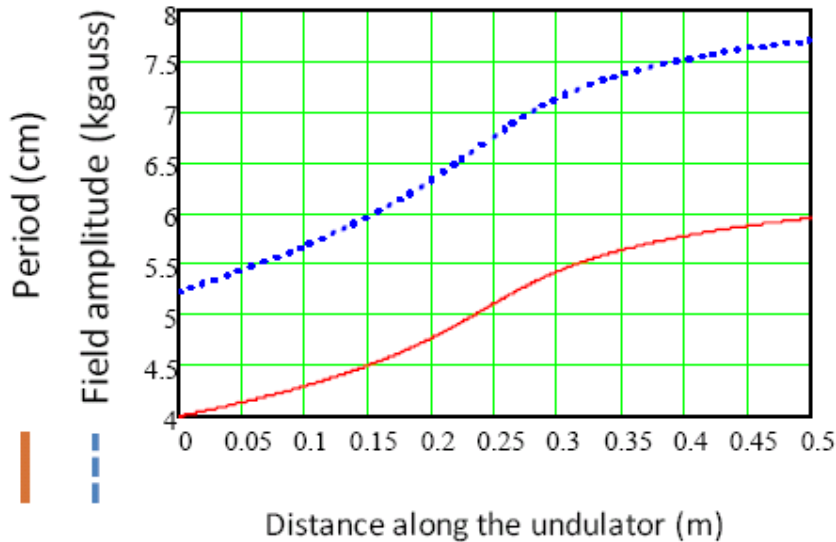
**vs.**

Helical

$$\frac{\partial \gamma}{\partial z} = kK_1 \cdot \frac{K}{\gamma} \sin(\psi)$$

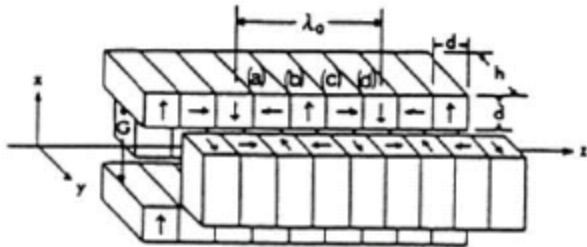
# Modified undulator tapering design

- Use commercially available NdFeB magnets.  $B_r = 1.22$  T
- Take into account not ideal laser transverse profile  $M^2 = 1.5$
- Provide large enough gap (15 mm) to minimize laser losses
  - >98 % transmission to allow for recirculating schemes.

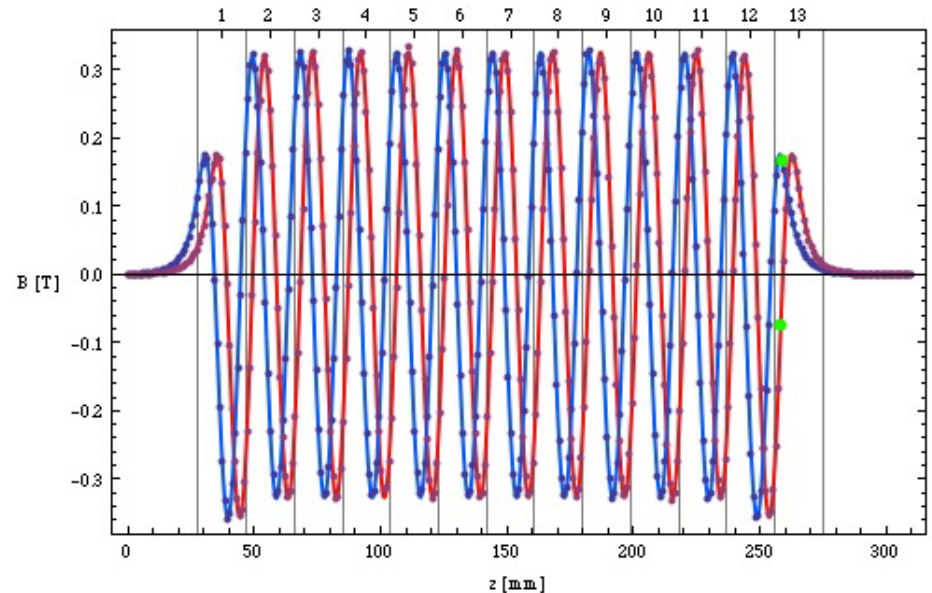
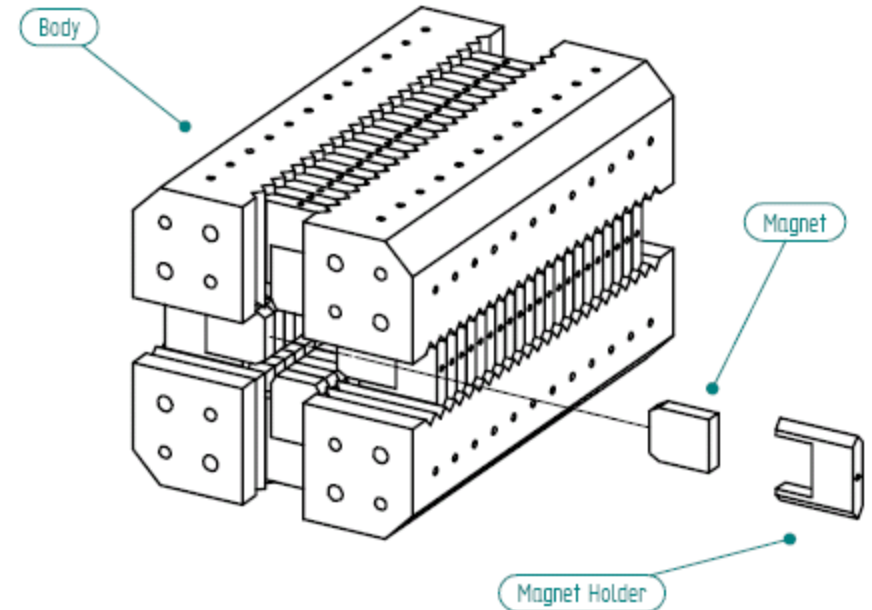


# Permanent magnet helical undulator

- Helical permanent magnet undulator.



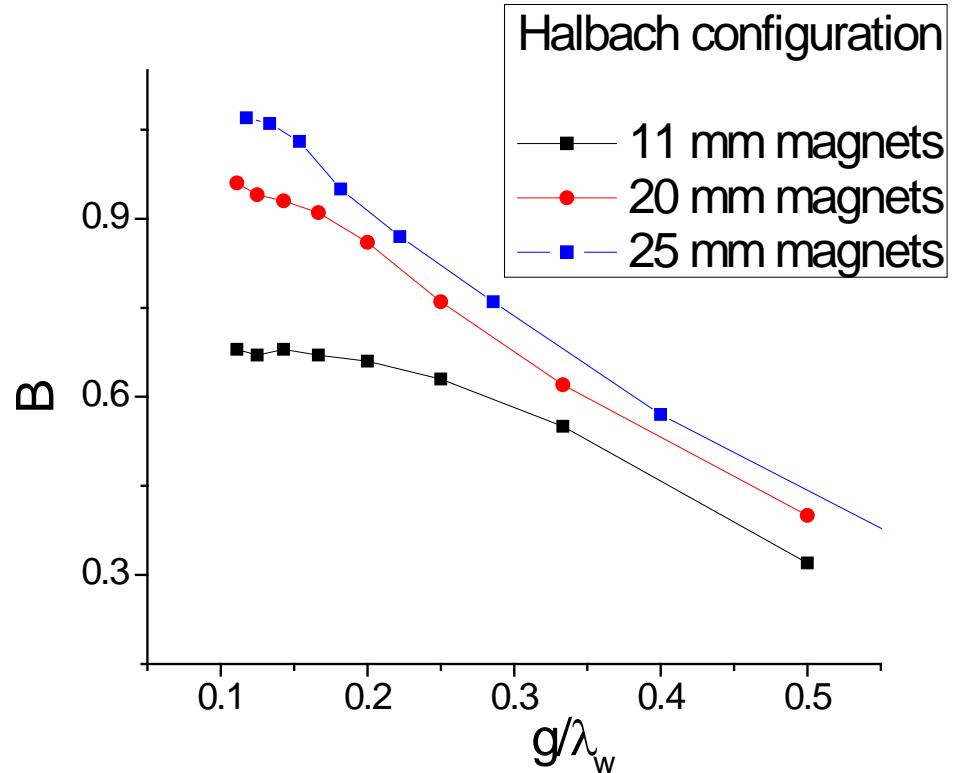
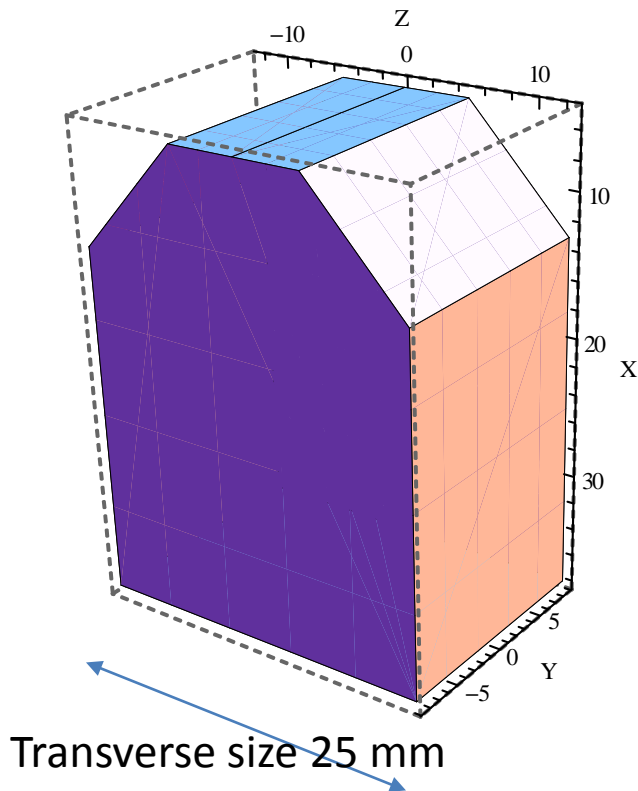
- Prototype (30 cm long) built and measured at UCLA
- Measurements in very good agreement with simulation predictions.





# Permanent magnet helical undulator optimization

- Transverse magnet size  $\sim \lambda / 4$
- Gap 1.5 cm
- Need to put magnets close together -> Trapezoidal shape.

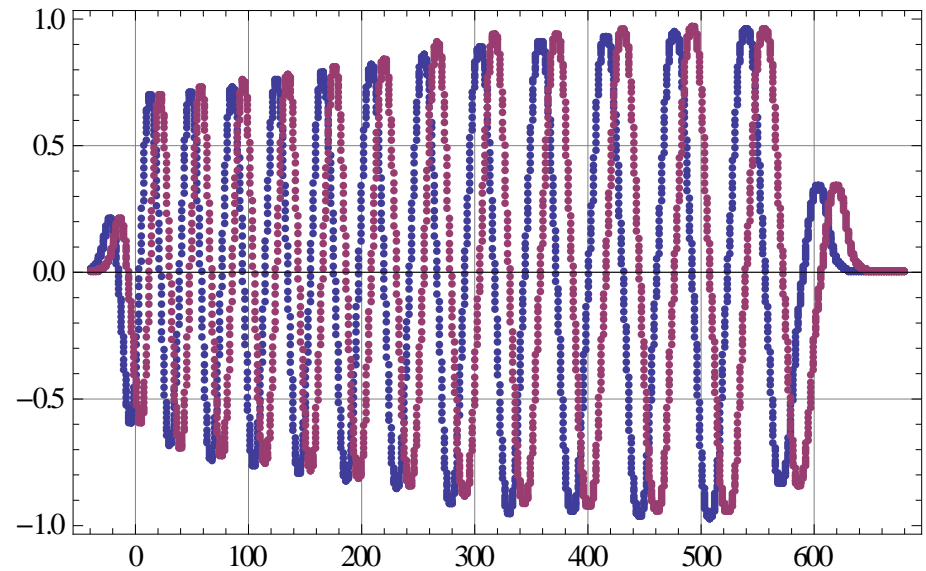
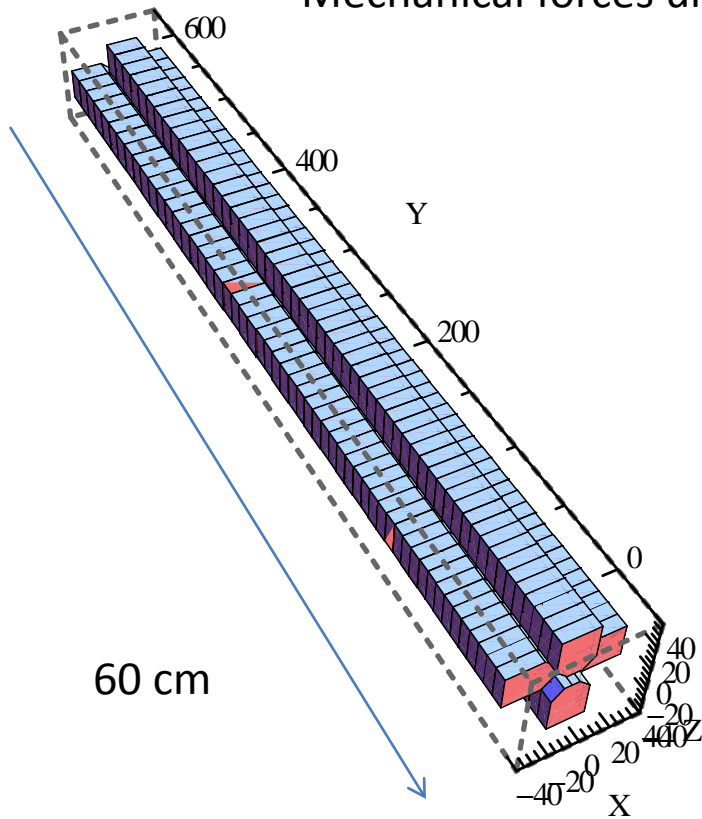


# 3D magnetostatic simulation

Use RADIA magnetostatic code

Evaluate demagnetization field for each magnet.

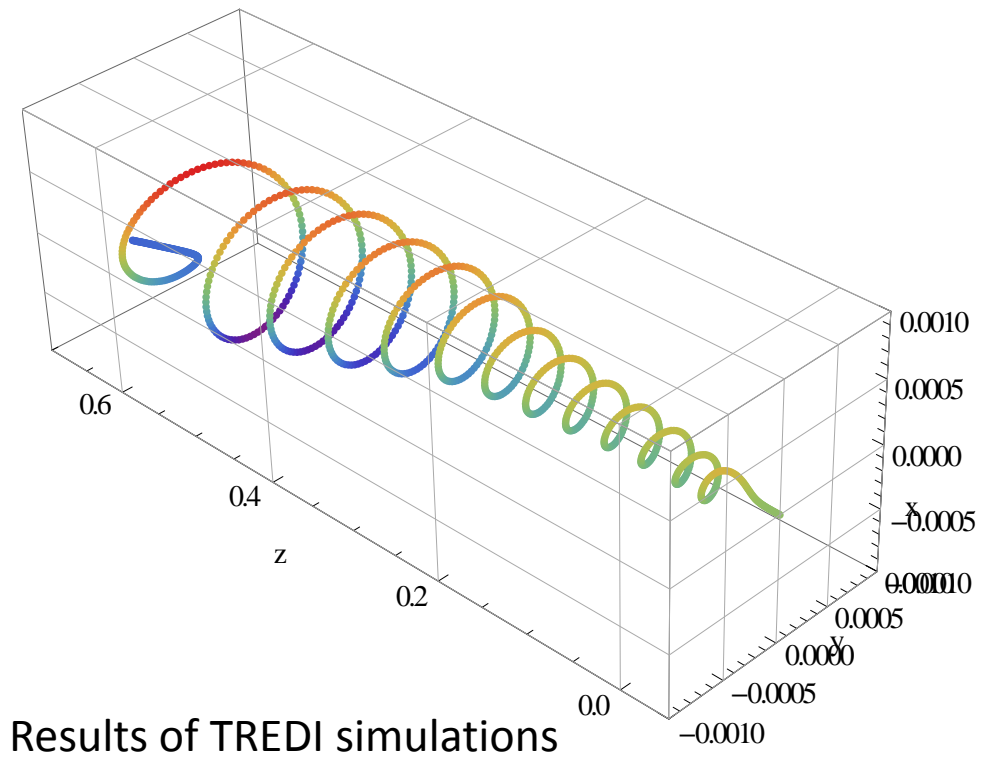
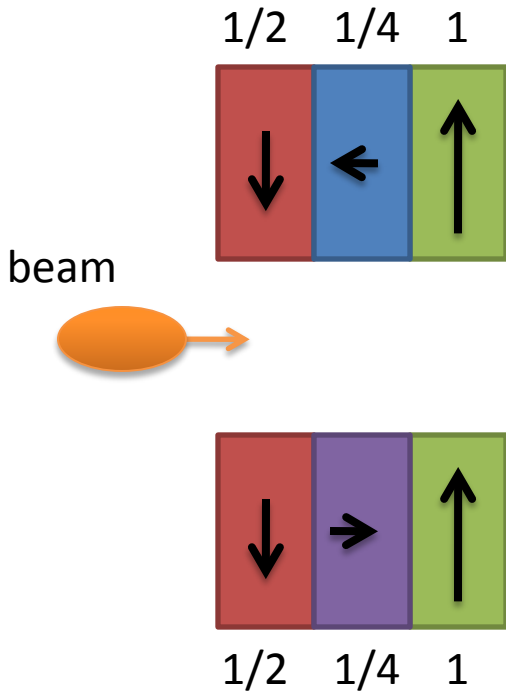
Mechanical forces under control.



# Trajectory of particles within helical undulator

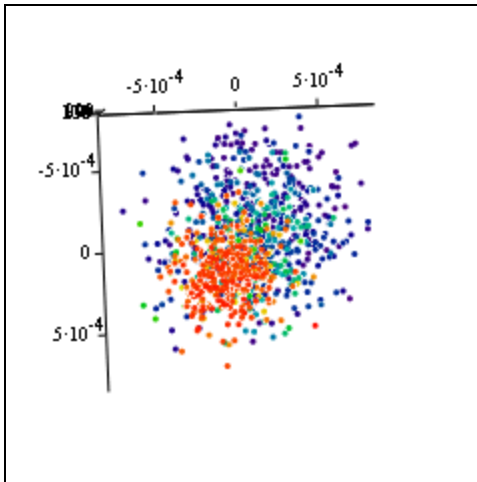
Need to choose end sections to minimize first and second integral  
Design for trajectory to oscillate around axis.

End section

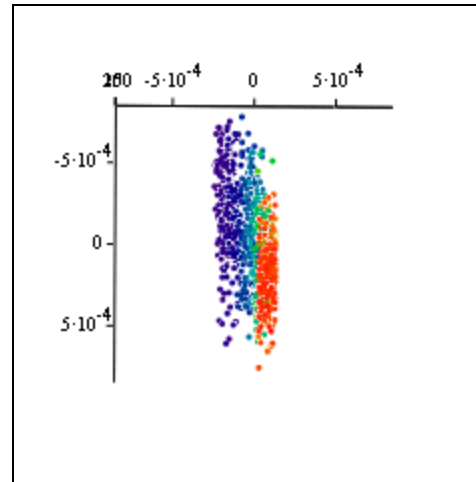


# Fully three dimensional simulations

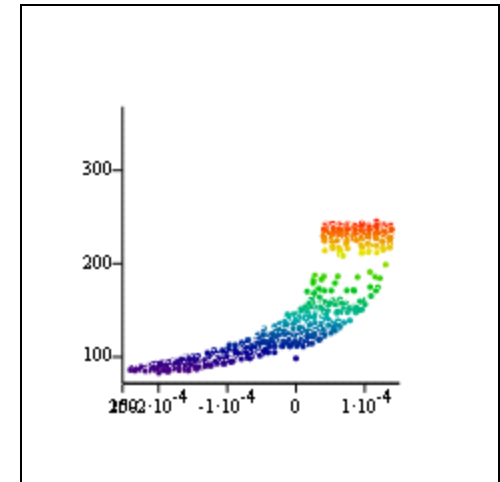
- Focusing effects included using 3dimensional field map from RADIA.
- Non accelerated particles will be separated both in energy and transverse position/focusing.
- Next step. Include radiation field evolution.
  - Modified GENESIS version. In progress.
  - Beam loading effects
  - Phase front distortion for recirculation



( $x_{part}$ ,  $y_{part}$ ,  $p_{zpart}$ )



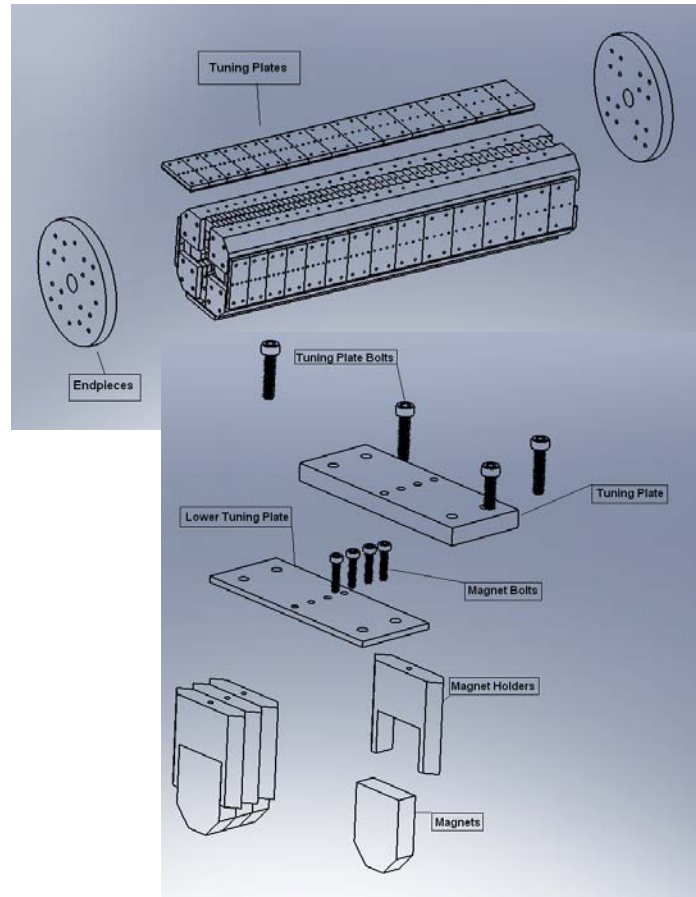
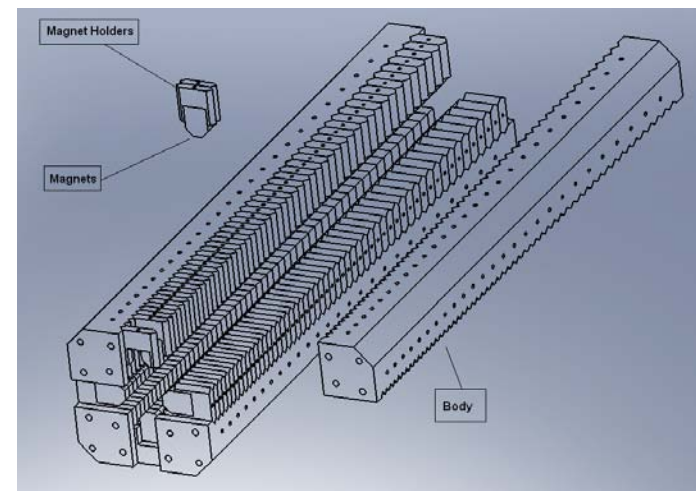
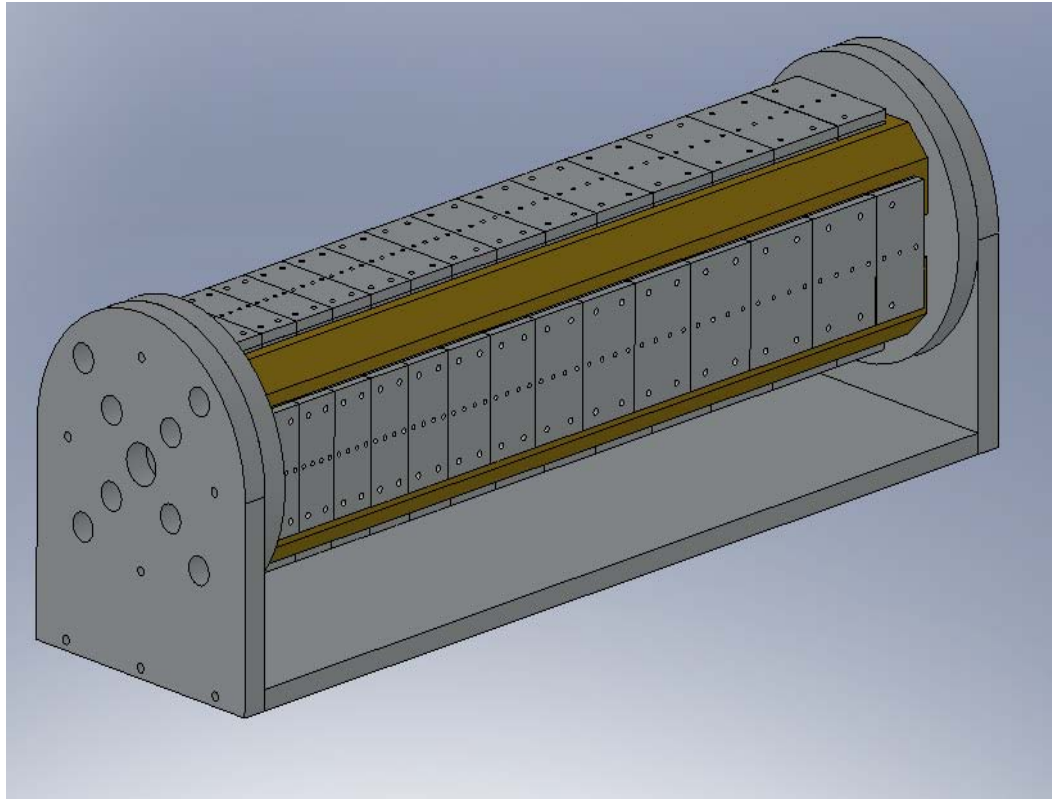
( $x_{part}$ ,  $z_{part}$ ,  $p_{zpart}$ )



( $p_{zpart}$ ,  $z_{part}$ ,  $p_{zpart}$ )

# Mechanical design of undulator

- Design finalized
- Drafted and out to the machine shop
- Magnets have been ordered. Delivery in 40 days.
- Beam pipe ordered.
- Assembly and B-field measurements to start before the end of 2010.



# Schedule

- Funding has been secured. DTRA + UCOP + DOE-HEP.
- Postdoc (R. Li) + graduate student ( J. Duris) started working on project this summer.
- Undulator construction (next six months)
- Single pass IFEL acceleration scheme
  - Beam time required starting Spring 2011
- Recirculation scheme would be very important.
  - First advanced accelerator to show this.
  - Dramatic increase in wall-plug efficiency.
- Need to advance IFEL simulation capabilities.