



Physics-Informed Deep Learning for Traffic State Estimation and Fundamental Diagram Discovery

Sharon Di, Ph.D.

Civil Engineering &
Engineering Mechanics

Data Science Institute

Data & innovative-
technology driven
Transportation Lab

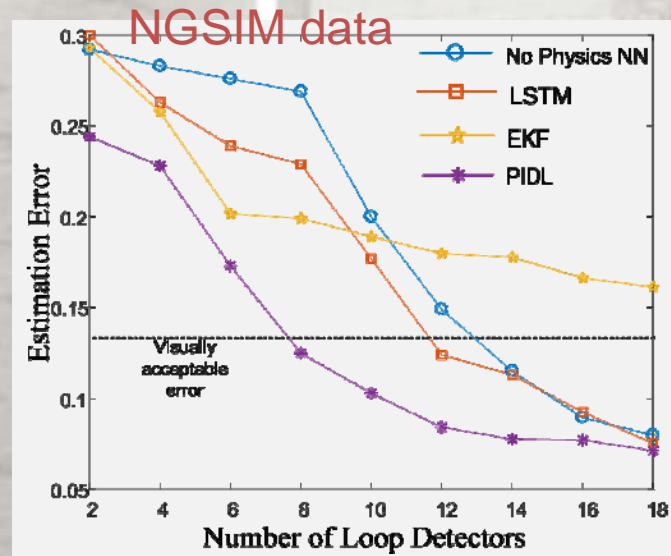
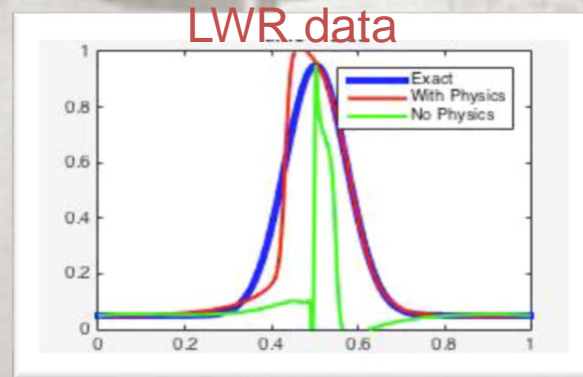
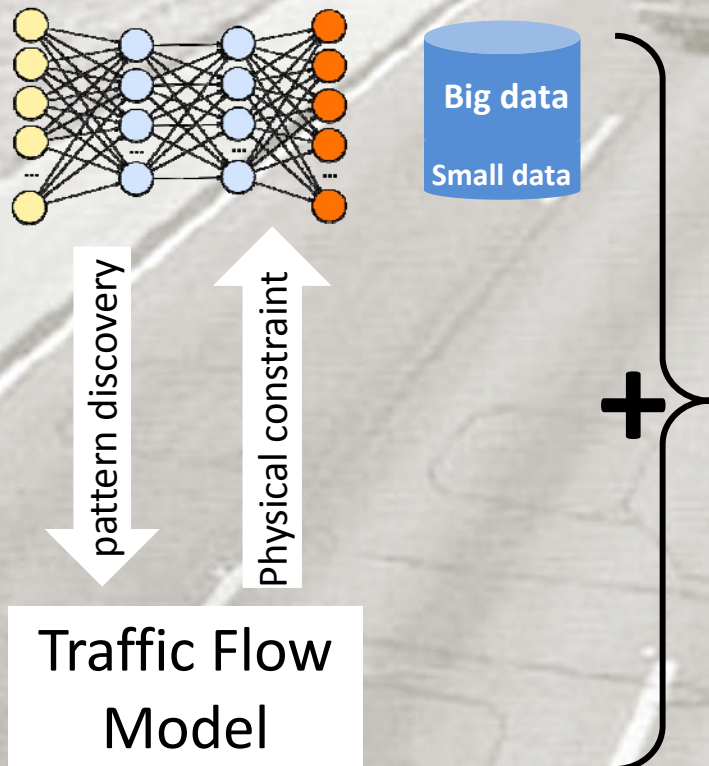


Zhaobin Mo / Dr. Rongye Shi (Civil), Kuang Huang / Prof. Qiang Du (Math)

Traffic State Estimation: Highlights

*Train neural network (NN)
w. sparse sensors?*

NN regularized by traffic models
outperform w. small data



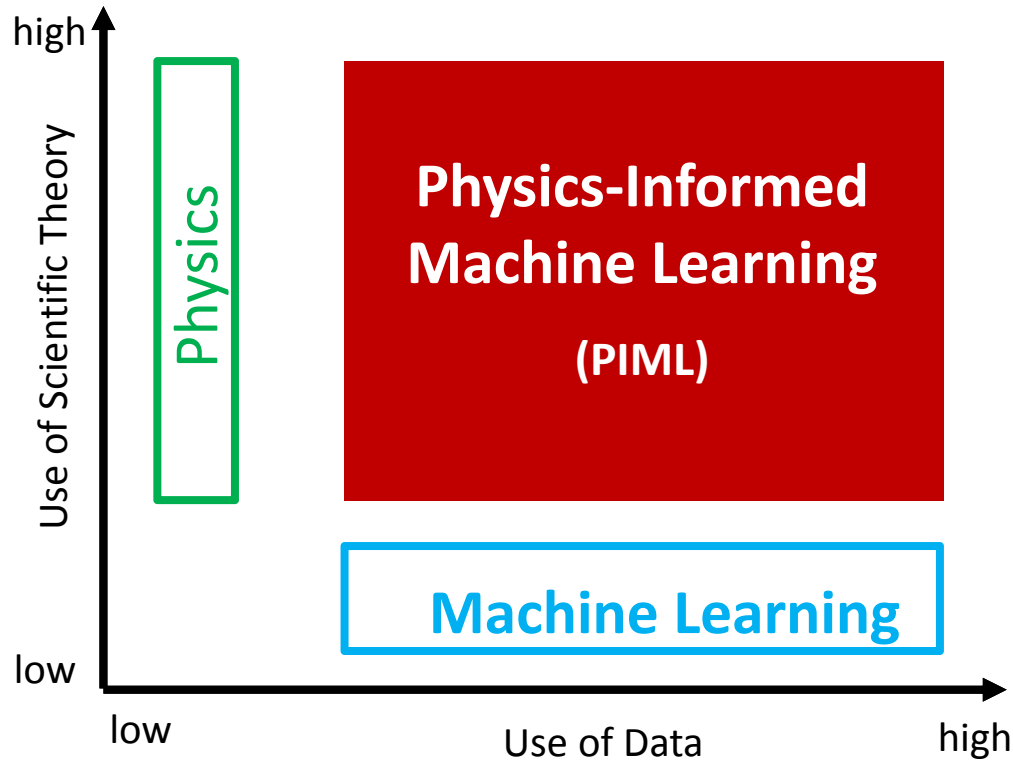
IoT: COSMOS Testbed

Cloud-Enhanced Open Software Defined Mobile Wireless Testbed for City-Scale Deployment

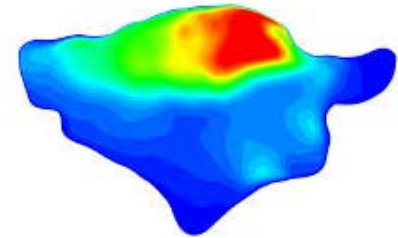
How to leverage data collected from IoT powered by CPS for real-time traffic state estimation?



Physics-Based vs. Data-Driven



Fluid Dynamics



Neuroscience



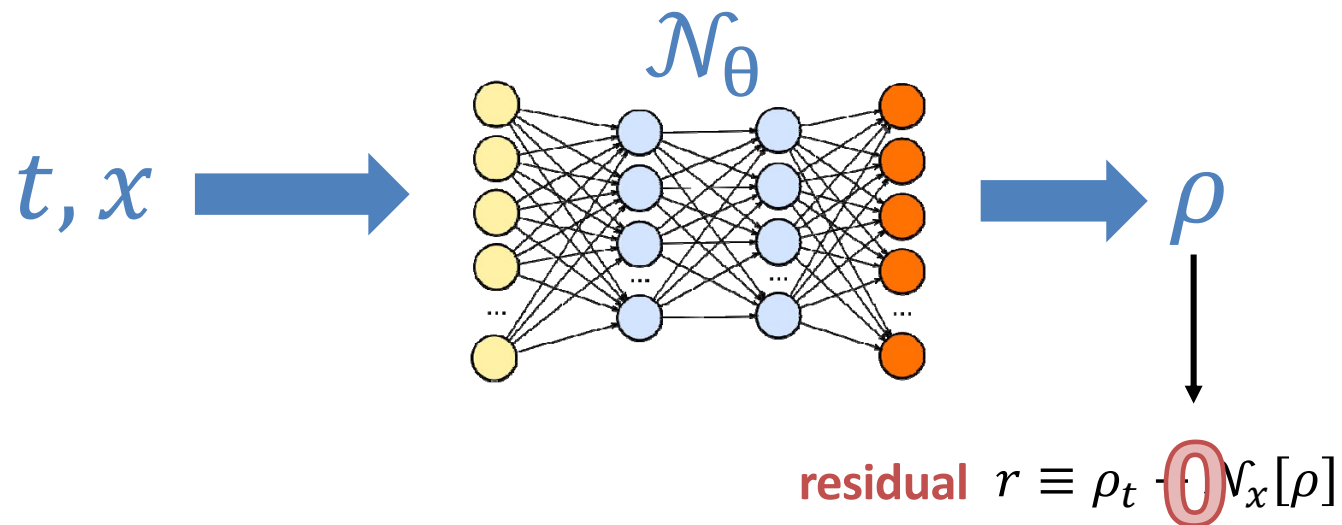
Data-Driven Solutions of PDE

5

$$\rho_t + \mathcal{N}_x[\rho] = 0, t \in [0, T], x \in \Omega$$

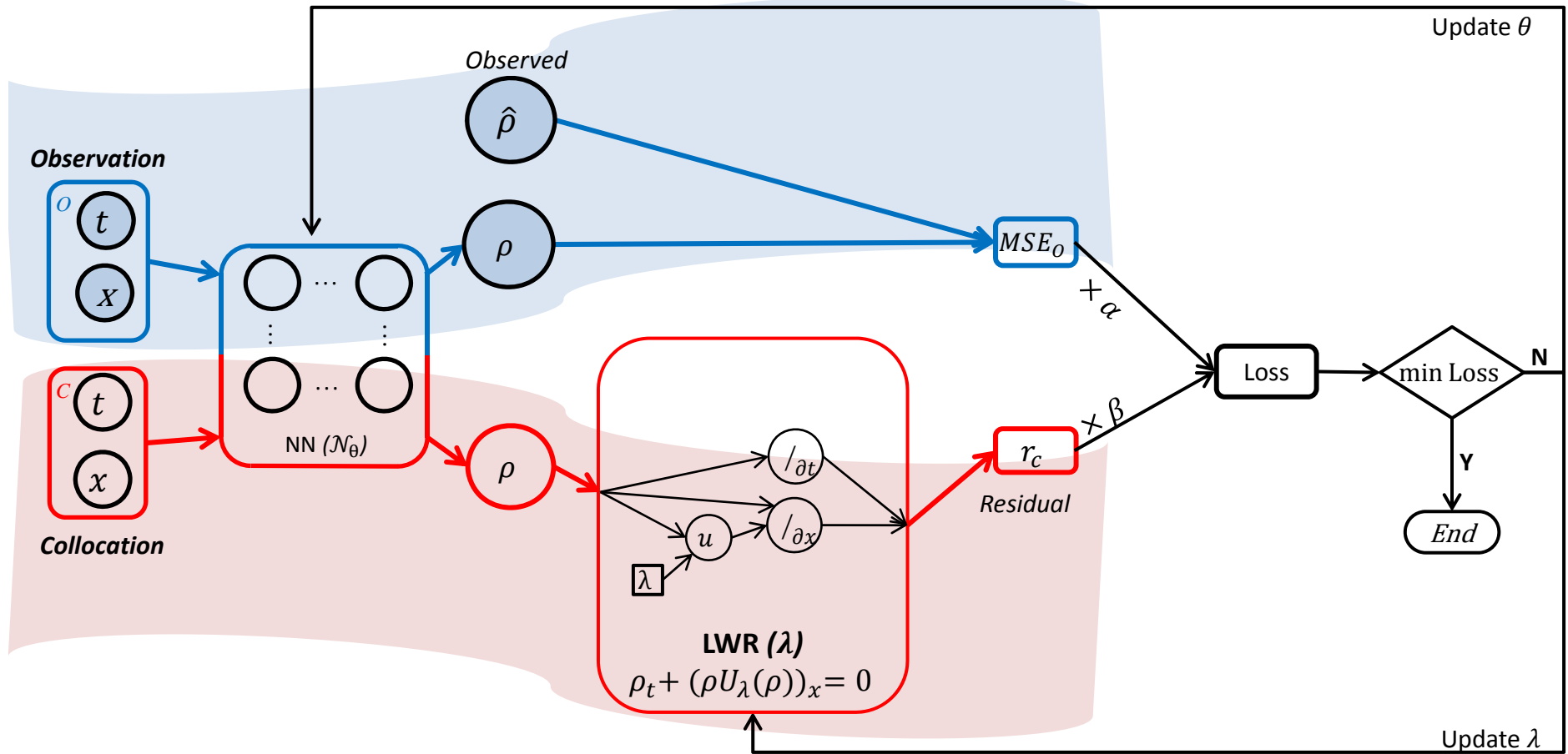
- $\rho(t, x)$: the solution of physical value (e.g., density/velocity field)
- $\mathcal{N}_x[\cdot]$: a nonlinear differential operator
- Ω : a subset of \mathbb{R}^D , denoting the high-dimensional physical space.

Goal approximate $\rho(t, x)$ by a neural network



[Raissi-Maziar (2017, 2019)]

Training PIML



[Shi, R., Mo, Z. and Di, X., 2021. *Physics Informed Deep Learning for Traffic State Estimation: A hybrid paradigm informed by second-order traffic models*. AAAI]

Data-Driven Solution of LWR Models

$$\rho_t + (\rho u)_x = 0, \quad x \in (0, 1), t \in (0, 3)$$

$$u = u_{max} \left(1 - \frac{\rho}{\rho_{max}} \right)$$

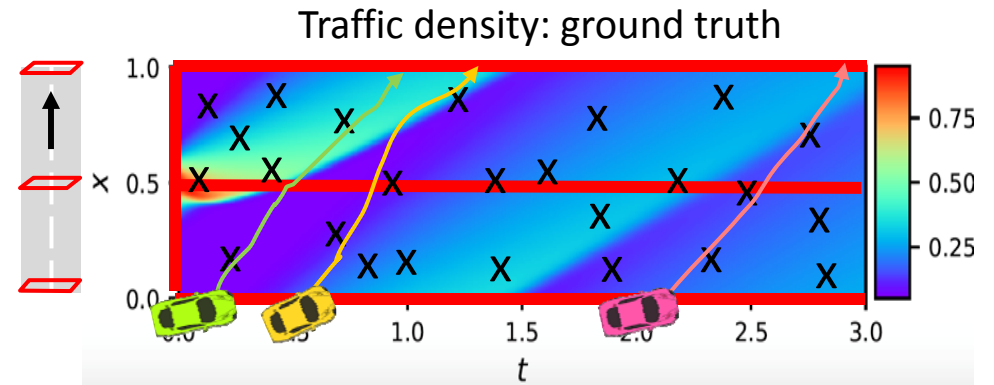
$$\rho(0, x) = \hat{\rho}_0(x) \text{ (initial condition)}$$

$$\rho(t, 0) = \rho(t, 1) \text{ (boundary condition)}$$

ring road

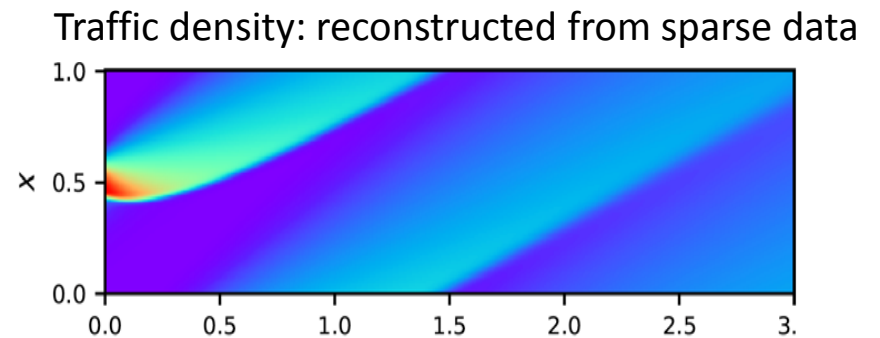
Observation (labeled) $\{(t_o^i, x_o^i), \hat{\rho}^i\}, i = 1, \dots, N_o$

Collocation (unlabeled) $(t_c^i, x_c^i), i = 1, \dots, N_c$



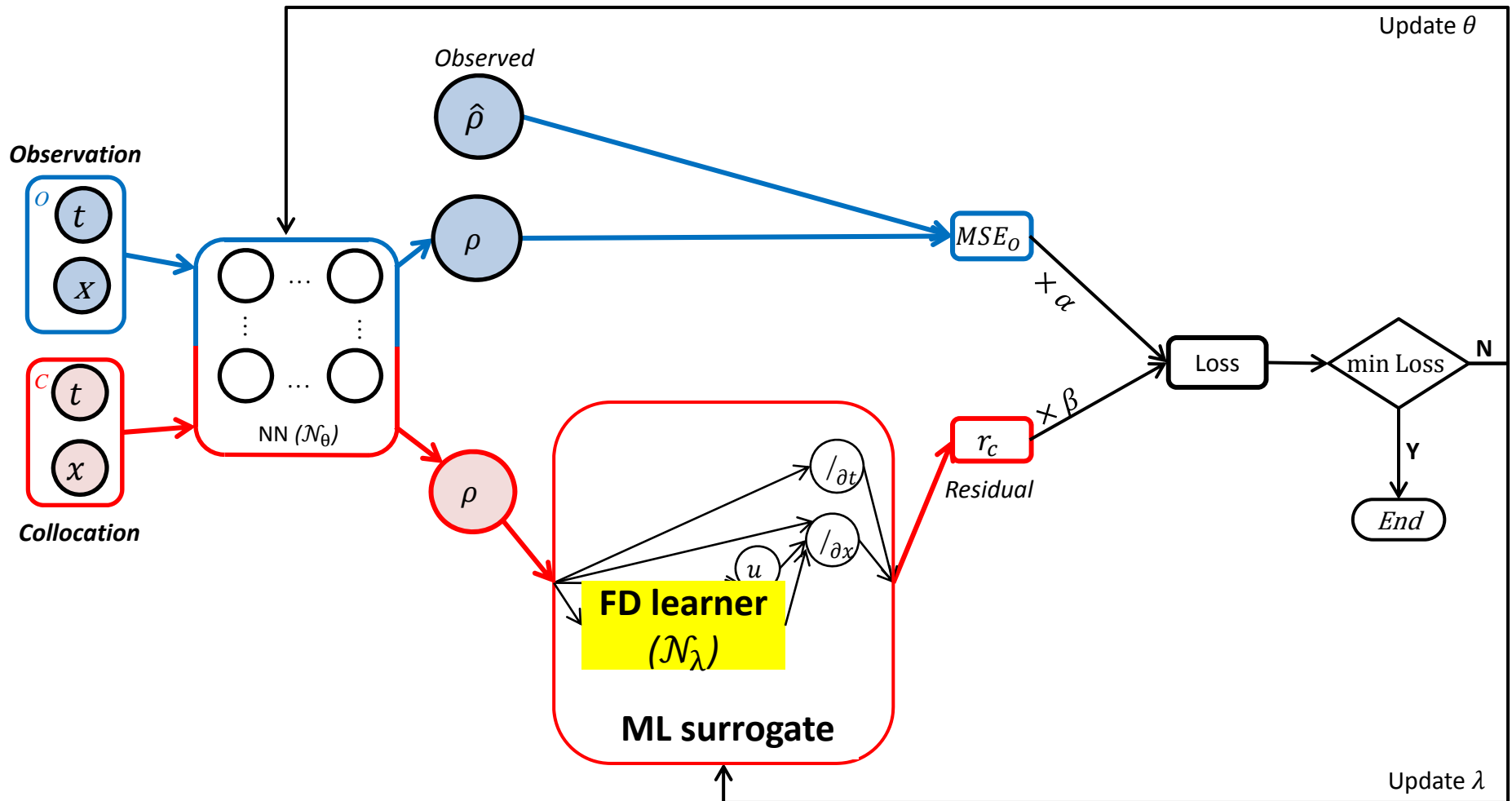
$$Loss = \alpha \underbrace{MSE_o}_{\text{Obs. discrepancy}} + \beta \underbrace{r_c}_{\text{Physics discrepancy}}$$

- ✓ Initial
- ✓ Boundary
- ✓ within domain



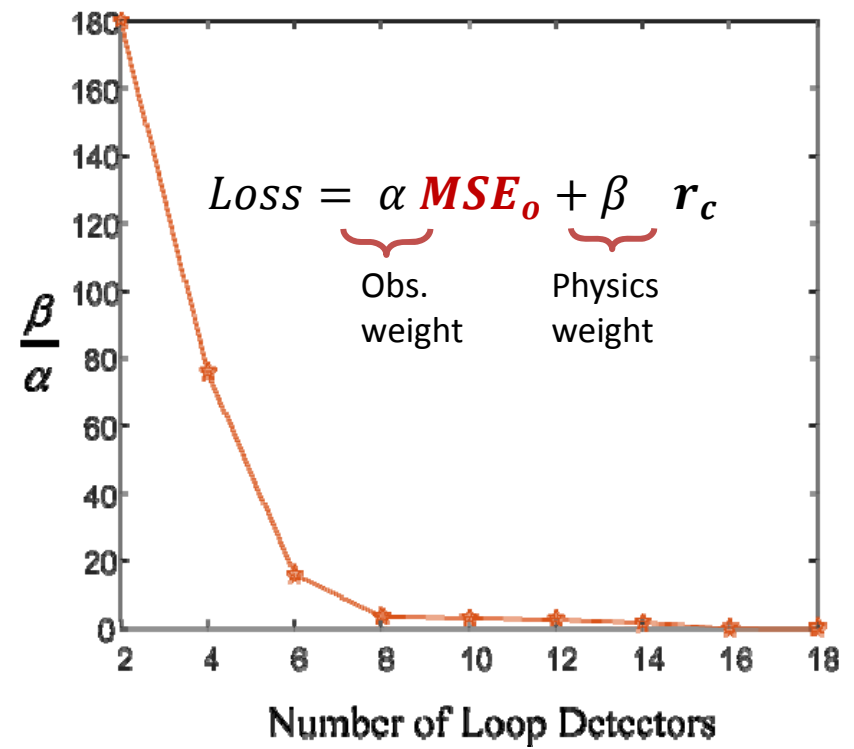
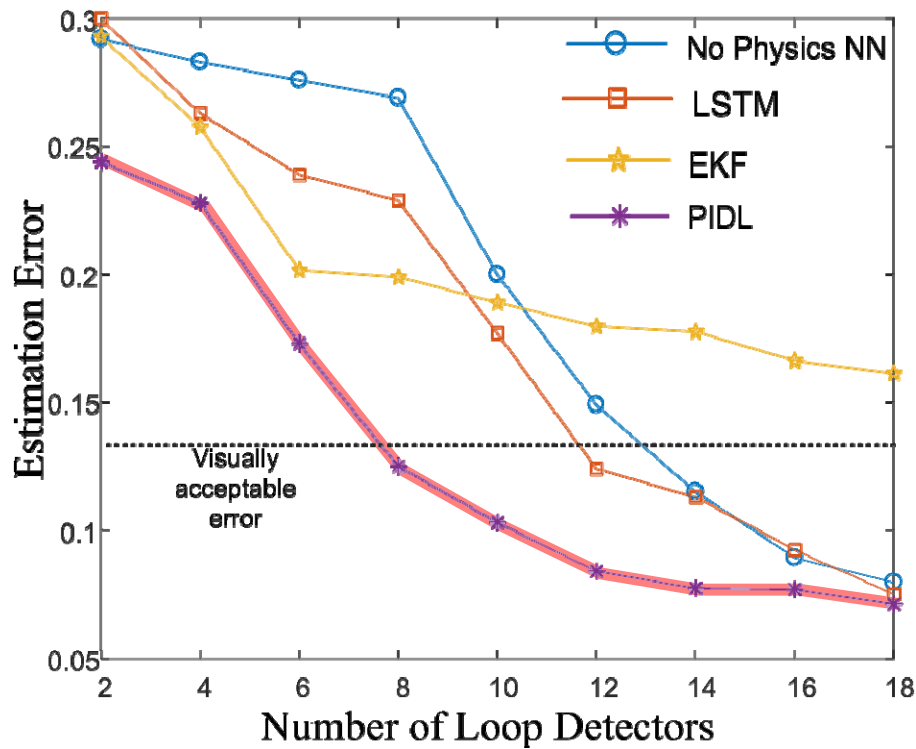
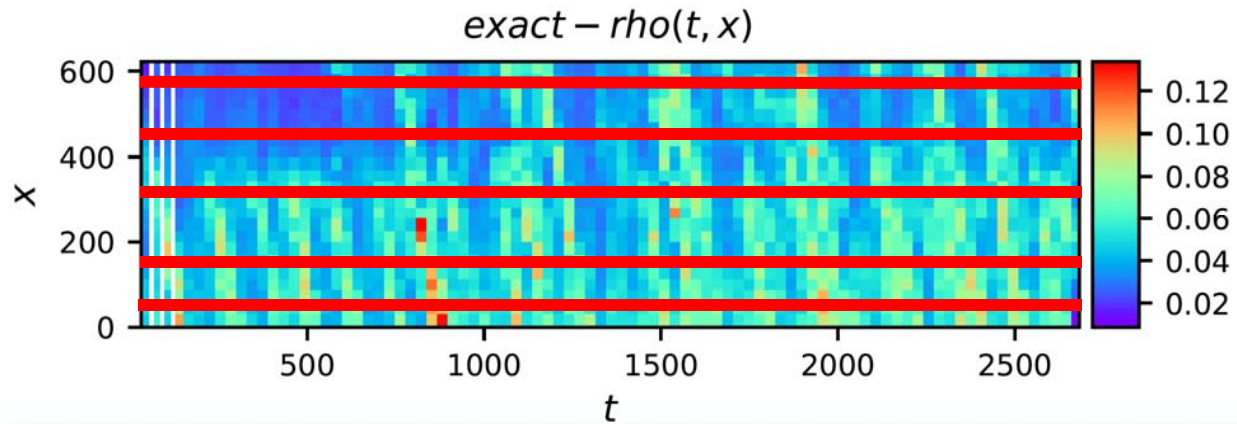
Fundamental Diagram (FD) Learner

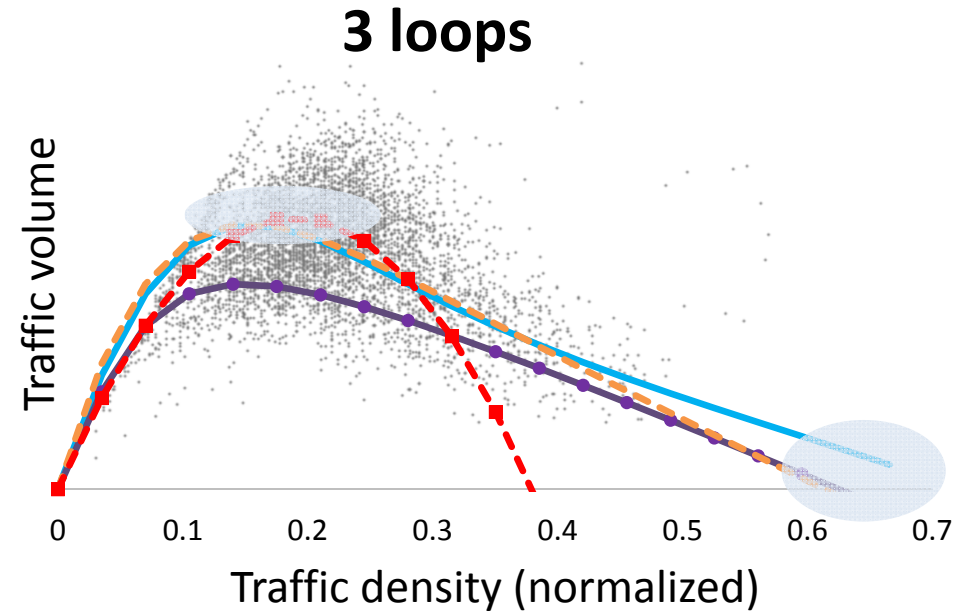
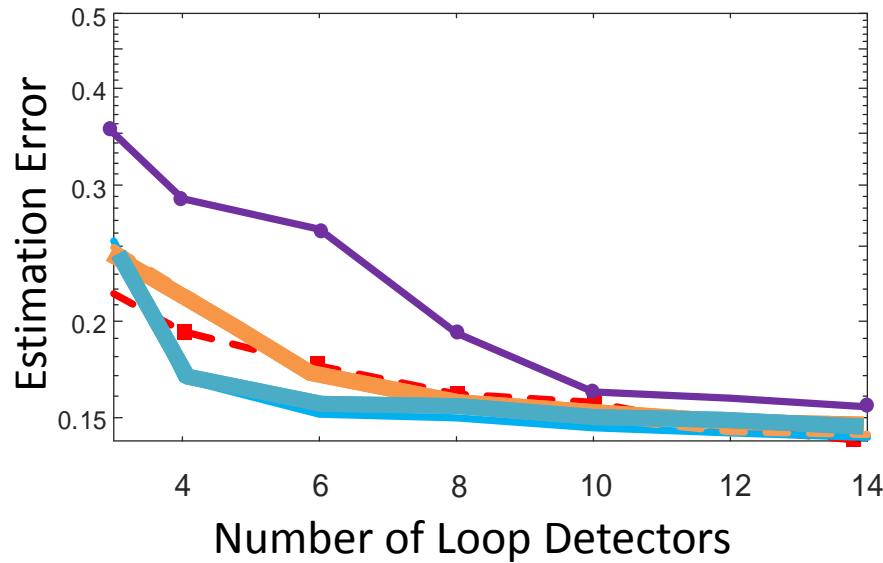
8



[Shi, R., Mo, Z., Di, X., 2021. A Physics-Informed Deep Learning Paradigm for Traffic State and Fundamental Diagram Estimation. IEEE ITS]

NGSIM: LWR as Physics





- LWR-PIDL+FDL
- LWR-PIDL(using LWR with 3-parameter FD)
- - ARZ-PIDL+FDL
- - ARZ-PIDL (using ARZ with Greenshields FD)

THANK YOU!

Questions?

